

A Congestion-Aware Routing Algorithms Based on Traffic Priority in Wireless Sensor Networks

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Abstract

Wireless sensor network allow the network manager to measure the observed events in a short radio range and give them an appropriate response. In many applications of wireless sensor network, due to the high volume of traffic, probability of congestion and packet loss increases. Congestion in sensor networks has a direct effect on energy efficiency and quality of service applications. Congestion may cause a buffer overflow, longer queuing time and higher packet loss. Packet loss not only reduces the reliability and quality of service application but also wastes energy. In this paper, a scheme for controlling congestion in wireless sensor network is proposed. The aim of the proposed method is to reduce congestion by considering the priority of data. In the proposed algorithm, according to the data priority, the packets will be classified. According to type of packet, traffic is redirected to control congestion in the network. Finally, the proposed algorithm is simulated and the result shows that the proposed algorithm improves the number of packet loss, energy consumption and average buffer size rather than the similar algorithm.

Keywords: Wireless Sensor Networks, Congestion Control, Traffic Prioritization, Routing.

1. Introduction

Romer and Mattern (2004) applied Wireless Sensor Networks (WSNs) for wireless networks consisting of distributed autonomous nodes to analyse physical or information of environmental such as temperature, pressure, sound, weather, and motion among others at different locations. Cerpa et al. (2001) presented a various range of sensors in civilian areas such as habitat observation. Schwiebert et al. (2001) presented for healthcare applications based on this WSNs (Kung and Vlah, 2003) and introduced object tracking for this model based on WSNs. Recently, the problem of congestion control and avoidance has been presented for attracted a lot of attention. Hence, many researchers presented the need of congestion control in WSNs. Researchers presented argue on this issue and provide numerical results, while a number of other documents like analyse and provide specific solutions on this problem (Sergiou and Vassiliou, 2013) (Sergiou, 2013) and (Antonioni and Antoniou, 2012). In many applications of WSNs, due to the high volume of traffic, congestion and packet loss probability increases.

Two important factors in WSNs are buffer overflow and link congestion. Buffer overflow occurs when the packet arrival rate increases more than packet service rate which occur in nodes near the sink (Sergiou, Antonioni et al., 2014). And link congestion, such as competition,

interference and bit error that this type of congestion occurs on the link.

A node in a WSN is a small embedded computing device that interfaces with sensors/actuators and communicates using short-range wireless transmitters. Such nodes work autonomously but this working to form a logical network in which data packets are routed hop-by-hop towards management nodes, generally called sinks or base stations. Sensors typically work under light load and suddenly become active in response to a detected or monitored event. In many applications, this can conclude in the generation of large, sudden, and correlated impulses of data that must be delivered to a small number of sinks without significantly disrupting the performance of the sensing application. This high generation rate of data packets is usually uncontrolled and often leads to congestion. In this state, collisions occur in the medium or in case of existence of an effective Medium Access Control (MAC) protocol, the node buffers overflow (Woo and Culler, 2001), resulting in random drops of data packets and increased delay. Dropped packets are a major handicap for these networks since they result in severe energy consumption (Wan et al. 2003). In the case that no countermeasures are taken, the power of congested nodes can be exhausted leading to the creation of routing "holes" in the network.

Mechanism of Congestion control is carried out in three sequential phases: congestion detection, notification and

counteraction. According to the challenges of WSNs and the importance of network congestion control, researchers have been done in this area. However, in the previous researches, congestion for packet priority is not efficiently controlled. In this paper, we propose a routing algorithm in which the next hop node is selected using buffer occupancy and residual energy of neighbour's nodes. In the first phase, the proposed algorithm attempts to avoid congestion using a predefined threshold. However, if congestion occurs, it will reduce it.

The remainder of this paper is organized as follows. In Section 2, a brief review of related works on congestion control protocols in WSNs are presented. Section 3 discuss on the proposed algorithm. Section 4 shows details of the simulations and evaluates for the performance of the proposed model. Finally, the conclusion is presented in Section 5.

2. Related Work

In the explained method for congestion control, the congestion is reduced or partly controlled, but these methods, lacks of an efficient model to control the congestion effectively in a network. Sergiou, Antoniou et al. (2014) reviewed, classified, and compared algorithms, protocols, and mechanisms that deal directly with congestion control and avoidance in WSNs. Chen and Yang (2006) suggested a congestion avoidance scheme based on buffer management style, that was the behind idea of flow control hop by hop in the credit. This design, applied a specific buffer to prevent the hidden station of congestion. Wan et al. (2003) presented Congestion Detection and Avoidance algorithm (CODA) for avoidance and congestion control in WSNs. This algorithm introduces the base of the field and it is one of the most used algorithms. A Fusion scheme has been proposed for mitigating congestion control in WSNs by Hull et al. (2004). Siphon has been proposed for a source-to-sink congestion control protocol by Wan et al. (2005).

Speed removes congestion with considering direction redirecting of entrance traffic in around the hot spot (Stankovic et al., 2003). The substituting direction may not have end to end large channel capacity for the placement of precursor traffic congestion.

Hierarchical Tree Alternative Path (HTAP) has been proposed by (Sergiou, Vassiliou et al. 2013. HTAP is a scalable and distributed framework for minimizing congestion and assuring reliable data transmissions in event based on networks and it is a hop-by-hop algorithm that employs an implicit way for informing the other node of the congestion. It reduces congestion through a resource control technique. Thus, when congestion is happening, paths of alternative are created from the source to reduce, using the set of a network's unused nodes, in order to safely transmit the observed data. The creation of alternative paths involves several nodes, which are not in the initial shortest path from the source to the sink. According to simulation results, the use of these nodes leads to a balanced energy

consumption, avoiding the creation of "holes" in the network and prolonging network lifetime.

Adaptive Rate Control (ARC) scheme has been proposed by Woo et al. in 2001. ARC cannot be used for any congestion detection or notification mechanisms. ARC uses an AIMD-like traffic control scheme to mitigate congestion, which works based on an intermediate node increases its sending rate by a constant.

A hop-by-hop node priority has been proposed by Wang et al. (2006) based on upstream congestion control protocol for WSNs. This scheme withdraw the congestion control protocols for argue in favour of providing equal fairness to each sensor node in a multi-hop WSN by attaching a weighted fairness to each sensor node.

A distributed and scalable mechanism has been proposed by Ee et al. (2004) based on Congestion Control and Fairness (CCF) for many-to-one routing in WSNs. The CCF provides congestion detection on the basis of packets service time, and congestion mitigation through traffic control.

3. Proposed Algorithm

In given to the importance of prioritizing pockets in various applications such as military and medical applications, most of the above methods do not consider priority package and packages all have the same priority. However, in our proposed algorithm packages have different priority. Also in the mentioned methods for redirecting traffic, one direction is used, that may have occurred inside the chosen route congestion. Also in this algorithm for routing and data transmission, hop by hop method is used. In hop by hop method each node according to the existing scenario selects the next hop. To determine the number of hops of each node, first, the sink sends a packet to its neighbours. Neighbours who receive this package are equal to number one. And the same procedure for each node is performed until to the end and the number of all nodes is determined.

The proposed algorithm congestion, including congestion detection mechanisms, congestion declaration and the reaction congestion, that is described in the following sections respectively.

3.1 Congestion detection mechanism

Congestion detection mechanism of our proposed algorithm based on the length of the queue and a threshold that is considered for each buffer. In this algorithm each buffer has two thresholds (Thr_1 , Thr_2). As if the buffer size is less than Thr_1 congestion has not occurred and if between Thr_1 and Thr_2 , the occurrence of congestion is likely and should stop it from happening and if buffer size is more than Thr_2 , it means congestion is occurred within node and should be reduced.

3.2 Congestion Notification Mechanism

Mechanism of congestion declaration in this algorithm is implicitly. Each node has neighbour buffer occupancy and accordingly determines whether congestion occurred within neighbouring node or not. The structure of the node is

Source node	Residual energy	Buffer occupancy	Hop counts
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Fig. 1. Hello packet structure.

Node numbers	Residual energy	Buffer occupancy	Hop counts
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Fig. 2. Neighbouring table structure.

3.3 Congestion Control Mechanism

Appropriate response is done according to the remaining energy nodes of neighbours and residual energy of occupied buffer. First case is a state that neighbour's node have a normal condition (means that all neighbours buffer capacity is less than the first threshold). Therefore node with the most remaining energy will be selected. The next hop of the whole package is in this node.

The second state is the case that neighbour nodes are candidate of occupied space capacity of their buffer between the first and second threshold. This is according to the said congestion mechanism detection; a state of congestion is likely and should be prevented. In this case the neighbouring node with the highest residual energy for low priority packet is selected and the neighbouring node with the lowest buffer occupancy for high priority packets is selected. In the second state, because the buffer occupancy is between the first and second threshold and this means, congestion is occurring so in this hop in addition to considering the remaining energy, we should also consider the occupied space to avoid filling buffer and change the rout packets to the less congestion rout.

The next hop shows the candidate neighbour node that their buffer occupancy is more than the second threshold. In this case, the last of a series of non-elected candidate with the highest residual energy will be selected.

3.4 Traffic Prioritization

Packet prioritization in sensitive areas such as military centres or medical care is very important because for the high-priority packets, better and optimize rout should be considered until the packets reach their destination on time and completely. For example in medical applications the packets made of different sensors and have different priorities, by sending the request, kind of disease and the priority should be identified.

In this method packets have different priority. Some have low priority and some have high priority. Each packet has a header bit as if this bit is one the packet priority is high, and if is zero it means that the priority is low.

shown in Fig. 1. The packet includes fields of the source node, that the address of source node placed in this field.

Package content as shown in Fig. 2 is stored inside the node table neighbourhood. The neighbour table includes some fields such as buffer occupancy, residual energy and the hop counts. After receiving a hello packet by each node, the node updates the neighbouring table rows.

3.5 Proposed algorithm

Congestion mitigation algorithm is described as follows. The mentioned method in algorithm is that if all neighbours candidate buffer is less than the first threshold (Thr_1) (line 1), then the next hop is to a high priority packet (NH_H) and low priority packet (NH_L), that its last remaining energy (E_{res}) node is higher than other candidate node (line 2). Otherwise, if some neighbours candidate node's buffer occupancy is higher than the first threshold (line 3), then some nodes are selected that their buffer occupancy is less than the first threshold (line 4). Therefore, the next hop for the packet with low priority is the neighbour node that its remaining energy is much higher than others node (line 5). For the packet with high priority a node of neighbour's node is selected that its buffer occupancy is lower than others neighbour's node (line 6). If buffer occupancy of all neighbouring nodes is more than the first threshold (line 7), thus, a node among the candidate neighbour's node is selected that their buffer occupancy is between the first and second threshold (Thr_2) (line 8). Therefore, the next hop for the packet with low priority is the neighbour's candidate node that the remaining energy is higher than other neighbour's node (line 9) and for the packet with the high priority a node among the neighbours is selected that the buffer occupancy is less than others (line 10). Finally there may be a circumstances which all the neighbours buffer occupancy is more than the second threshold (line 11). In this case, next hop for packets with high priority and low priority is the non-candidate neighbour's node that has the most remaining energy (line 12) and at the end line 13 shows the end of algorithm.

In the example of Fig. 3, we want to control congestion with the proposed mechanism. We assume the maximum buffer occupancy is 100, the first threshold 85 and the second threshold 95.

3.6 An example

In this example, we want to select the next hop to node 2 according to Table 1. The contents of this table are nodes from the neighbourhood table that get closer from node 2 to the sink. Here according to proposed algorithm, it is a mode that some of the neighbour's candidate node, their buffer

occupancy is less than the first threshold and some is more than the first threshold, so nodes 3 and 5 are selected. For the low priority packets node 3 is selected because the remaining energy is higher.

In the first stage, for the high priority packets according to the Table , nodes 3 and 5 are selected and then node 5 because of the less buffer occupancy is selected.

Algorithm: Congestion Mitigation

Input: N , Thr_1 , Thr_2

Output: NH_L , NH_H

1. If $(Bo_i \leq Thr_1, \forall i \in N)$ then

2. NH_L, NH_H = the element of N with $\max E_{res}$
3. else if $(Bo_i \leq Thr_1, \exists i \in N)$ and $(Bo_i > Thr_1, \exists i \in N)$
4. $N' = \{i \mid Bo_i \leq Thr_1, i \in N\}$
5. NH_L = the element of N' with $\max E_{res}$
6. NH_H = the element of N' with $\min Bo$
7. else if $(Bo_i \geq Thr_1, \forall i \in N)$
8. $N' = \{i \mid (Bo_i \geq Thr_1) \text{ and } (Bo_i < Thr_2), i \in N\}$
9. NH_L = the element of N' with $\max E_{res}$
10. NH_H = the element of N' with $\min Bo$
11. else // $Bo_i \geq Thr_2, \forall i \in N$
12. NH_L = the element of N with $\max E_{res}$
13. End if

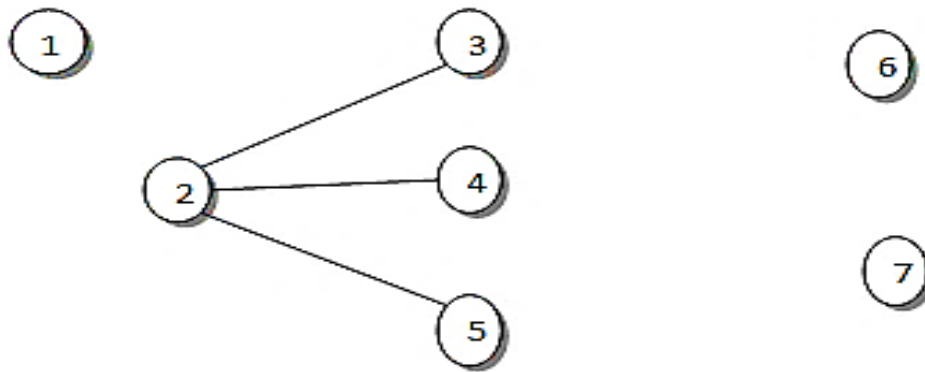


Fig. 3. An example of the proposed algorithm.

4. Performance Evaluation

In this section, the performance evaluation of the proposed algorithm is provided. The proposed algorithm is compared to the HTAP. In Table 2, simulation parameters are given. The parameters of this table are used in different scenario of network.

For evaluating the proposed algorithm, various metrics taken into account that are as follow: the average buffer occupancy of nodes, packet loss, and energy consumption.

In this section the simulation results by use of charts are analysed. In all figures, the proposed algorithm is compared with HTAP algorithm, as a similar mechanism for redirecting traffic.

4.1 Average buffer occupancy

Fig. 4 shows average buffer occupancy of nodes. As it is clear in Fig. 4, average buffer space nodes in the proposed algorithm is less than HTAP. The reason of this decrement is that the proposed algorithm with considering threshold of first and second buffer, control entrance traffic into the node and try to buffer space does not exceed the second threshold.

4.2 Packet loss rate

One of the important cases for packet drops is filling of buffer nodes. Fig. 5 shows the number of packet loss in the proposed algorithm rather than to HTAP algorithm. It is clear in the figure that the packet loss in the HTAP algorithm increases because of the limited selected routes, while the proposed algorithm has the lower dropped packets. The reason of this reduction is that the proposed algorithm performs the buffer management, and redirecting traffic route that causes reduction congestion in network nodes and finally reduction of removing packets.

4.3 Energy Consumption

Energy problem in sensors, in most of the algorithms is considered as a challenge. Fig. 6 shows the average energy consumption of sensors.

The proposed algorithm has lower energy consumption than HTAP algorithm. The cause of this reduction is that in the proposed algorithm, the number of dropped packets is less than HTAP algorithm.

Table 1

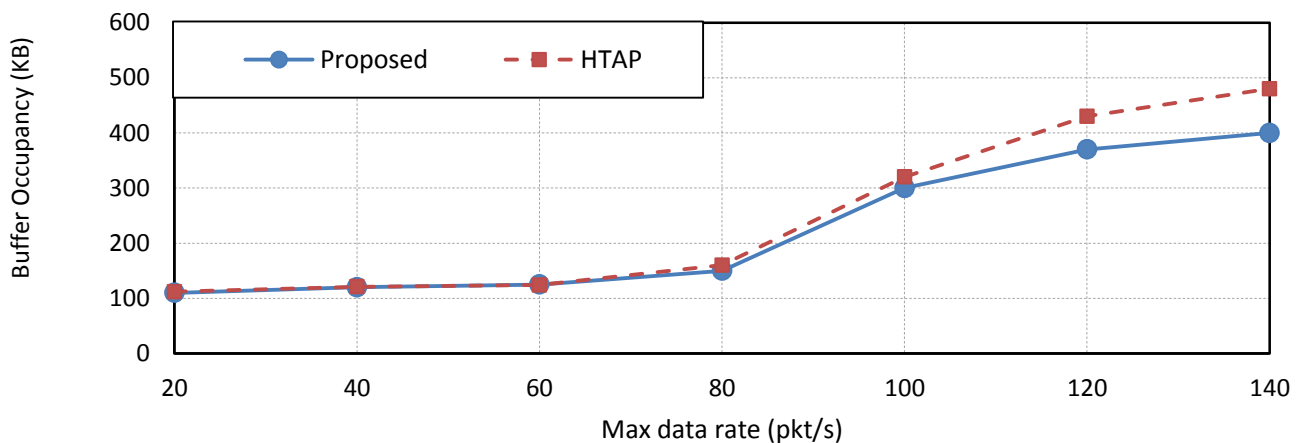
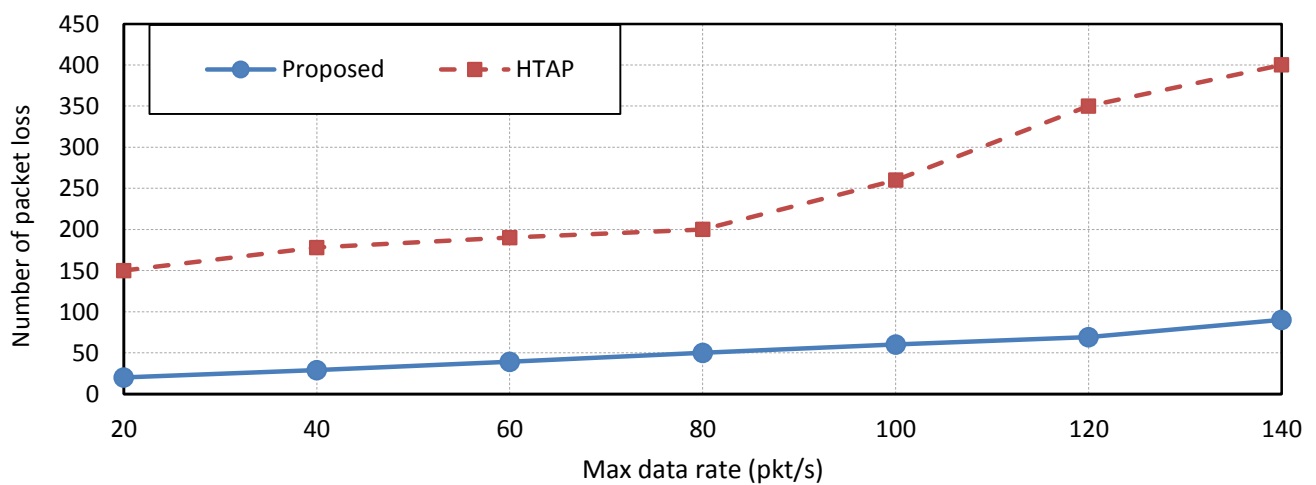
Neighbouring table of candidate node number 2.

Residual energy	Buffer occupancy	Node
1.8	80	3
1.9	90	4
1.75	70	5

Table 2

Simulation parameters.

Parameters	Value
Area(m*m)	100*100
number of node	100
Initial energy(Joule)	10
Buffer occupancy (Byte)	512
Max data rate (kbps)	250
Package size (bit)	1024
Range of sensors(m)	20
Time Simulation(S)	1000

**Fig. 4.** Empty average buffer occupancy during the time of the simulation.**Fig. 5.** Shows Number of packet loss.

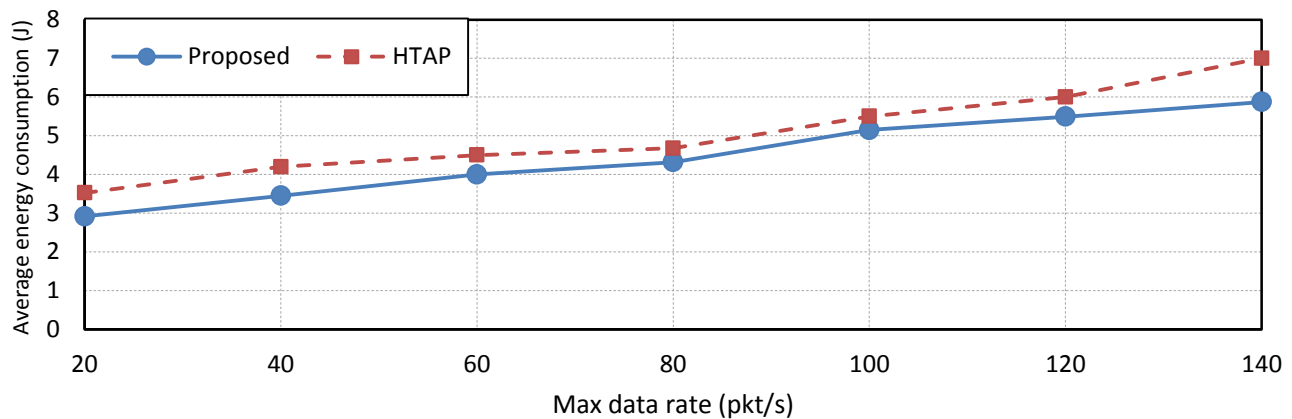


Fig. 6. Average energy consumption.

5. Conclusion

The issue of congestion controlling in wireless sensor networks is one of the important issue. In this paper, we attempted to control congestion in wireless sensor networks by using buffer management. Also with congestion controlling, we reduce the rate of packet loss. The proposed algorithm was simulated using Matlab software. The simulation results were analysed. The obtained result showed that the proposed algorithm prevents congestion, by using buffer management and redirecting traffic and accordingly reduces the congestion.

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